

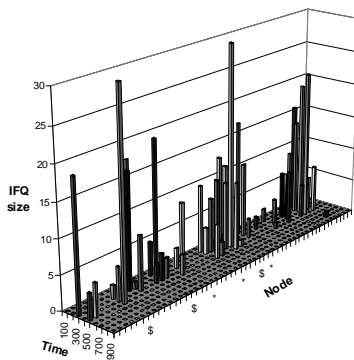
## Homework #3

- ❑ Goal: Want to know that nodes undertake the role of packet forwarding uniformly – packet queue size distribution.
- ❑ Setup: 50 nodes in  $300 \times 1500$  m<sup>2</sup> network based on random waypoint mobility with the maximum speed of 5m/s and the pause time is 0, 500 and 900 seconds. Simulation time is 900 seconds. 20 CBR sources send 4 512-byte packets per second. AODV is used. Use RTS/CTS.
- ❑ Output: Show IFQ sizes of all nodes at 100 second-interval. Throughput and delay curve. Explain what's happening.

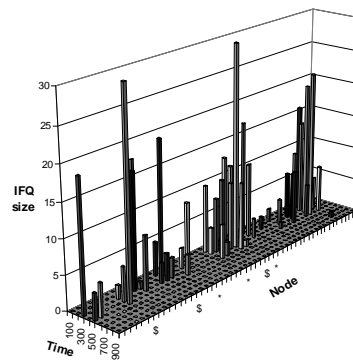
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## Homework #3



*Pause = 0*



*Pause = 500*

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# Command Method

## ❑ ~queue/priqueue.cc

```
int PriQueue::command(int argc, const char*const* argv)
{
    if (argc == 2 && strcmp(argv[1], "reset") == 0)
    {
        Terminate();
        //FALL-THROUGH to give parents a chance to reset
    }

    /*****
    static int len = 0;
    if (argc == 3 && strcmp(argv[1], "ifq-len") == 0) {
        len = length();
        FILE* fp = fopen(argv[2], "a");
        fprintf(fp, "%d", len);
        fclose(fp);
        return (TCL_OK);
    }
    if (argc == 3 && strcmp(argv[1], "ifq-len2") == 0) {
        FILE* fp = fopen(argv[2], "a");
        fprintf(fp, "\n", len);
        fclose(fp);
        return (TCL_OK);
    }
    *****/

    return DropTail::command(argc, argv);
}
```

*Don't forget to  
"Make"*

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# Command Method

## ❑ In the TCL script

```
for {set i 0} {$i < $val(nn)} {incr i} {
    set node_($i) [$ns_ node]
    $node_($i) random-motion 0           ;# disable random motion
    set priQ_($i) [$node_($i) set ifq_(0)]
}

$ns_ at 100.0 "getQLen $val(nn)"

proc getQLen { num } {
    global ns_ priQ_
    set interval 100.0
    for {set i 0} {$i < $num} {incr i} {
        $priQ_($i) ifq-len ifq-sz.tr
    }
    $priQ_(0) ifq-len2 ifq-sz.tr
    set now [$ns_ now]
    $ns_ at [expr $now+$interval] "getQLen $num"
}
```

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