

Path-centric On-demand Rate Adaptation for Mobile Ad Hoc Networks

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Abstract—Exploiting the multirate capability in *mobile ad hoc networks* (MANETs) is more complex than in single-hop WLANs because of the rate-distance and rate-hop count trade-offs. This paper proposes *Path-centric on-demand Rate Adaptation for MANETs* (PRAM) protocol. A unique feature that sets PRAM apart from most of previous studies is its *path-centric* approach. While others focus on finding the best data rate for each link and offering a routing path as a collection of links at their best rates, PRAM finds the best data rate for a source-destination pair and then, dynamically adapts it based on path lifetime and other factors. Another distinctive feature of PRAM is that it can be seamlessly incorporated with an on-demand routing protocol. Extensive performance study based on ns-2 has demonstrated that PRAM achieves as much as 71.7% higher packet delivery ratio than fixed-rate cases (6~54Mbps) and as much as 43.2% higher than the multihop version of the well-known ARF mechanism in a wide range of network scenarios. It is also shown that PRAM is capable of using a mixture of data rates in an adaptive manner.

Index Terms—Multirate adaptation, Mobile ad hoc networks, Path lifetime, IEEE 802.11, Spectral efficiency.

I. INTRODUCTION

With the availability of multirate capability in radio hardware and its inclusion in IEEE 802.11a/b/g, research community is trying to figure out how to exploit this capability to improve the network performance [1]–[7], [9]–[14], [18]–[22]. Those efforts can largely be categorized according to whether they target on single-hop WLANs or multihop *mobile ad hoc networks* (MANETs). Exploiting the multirate capability in single-hop WLANs is relatively simple because a mobile node has only one communication partner (*access point* or AP) and no more than one communication can concurrently happen. Therefore, each node can individually optimize its data rate for the communication link to the AP [2], [3], [11], [12]. For example, in *Auto-Rate Fallback* (ARF) [12], a node lowers its data rate if it experiences consecutive transmission failures and increases its data rate upon a number of consecutive transmission successes.

On the other hand, exploiting multirate capability in MANETs is admittedly more complex because of mobility and multihop routing. First, note that a higher data rate is achieved by using a more spectrally efficient modulation scheme and thus, requires high *signal-to-interference-noise ratio* (SINR). This in turn, mandates a shorter communication range or a larger number of hops for a given source-destination node pair. Due to this rate-distance or rate-hop count tradeoff, high

data rates are not always preferable. Second, due to the effect of inter-hop interference and almost identical interference range regardless of data rates, a high data rate brings in lower performance benefit than normally expected. Third, node mobility could break high-rate (short-range) links more easily, leading to a higher control overhead for maintaining active routing paths in a mobile environment.

A great deal of work on multirate adaptation has been reported in the context of multihop networks due to its potential in many interesting applications including *wireless mesh networks* [7], [9], [10], [13], [14], [18]–[21], [24]. Typically, they have concentrated on developing a rate-aware link cost which is then integrated with a multihop routing algorithm to find the path that minimizes the total cost.

However, most of previous studies target on static networks and/or employ *proactive* routing algorithms such as *Destination-Sequenced Distance Vector* (DSDV) [16] as the underlying routing protocol [6]–[8], [27], [30]. Proactive routing algorithms could be a reasonable choice in static networks. However, they incur a high control overhead in a mobile multirate environment because a “larger volume” of route information must be exchanged “more frequently.” In other words, each node is required to keep track of and exchange the status of all its links at all available data rates increasing the control overhead. More seriously, the nodes need to exchange route information much more frequently than in conventional single-rate network, where the frequency is set to, for example, 12 seconds [26] under a typical MANET scenario. However, in a multirate environment, a high rate link could survive only for a shorter duration, demanding much more frequent information exchange to maintain the link status up-to-date.

This paper proposes *Path-centric on-demand Rate Adaptation for MANETs* (PRAM) protocol that is a rate adaptation scheme, seamlessly incorporated with an on-demand routing protocol, called the *Ad-hoc On-demand Distance Vector* (AODV) [17]. To the best of our knowledge, this is the first paper that addresses the design of multihop routing in a mobile, multirate environment. A unique feature that sets PRAM apart from most of the previous studies is its *path-centric* approach. While others focus on finding the best data rate for each link to find an optimal path as a collection of links, PRAM finds an optimal data rate for a given source-destination pair. We believe this path-centric approach better fits in a multirate MANET than *link-centric* approaches be-

cause of its significantly lower control overhead and a simpler route discovery and maintenance procedure. On the other hand, PRAM dynamically adapts the data rate of a routing path depending on its robustness or lifetime, which is in turn affected by several factors including source-destination distance, traffic, and mobility conditions. Also, PRAM allows a node to adapt its link rate individually based on the ARF principle [12].

Extensive performance study based on *ns-2 network simulator* [15] has been conducted to evaluate the performance of PRAM. It is compared against single-rate cases and the multi-hop version of ARF, called *MH-ARF*, where each node applies the ARF rule to each link individually. Our study indicates that the 6Mbps case performs better than the 54Mbps case when the network is sparse but it is the opposite when the network is dense. However, PRAM achieves the best performance in the entire range of node density. Packet delivery ratio (PDR) is improved as much as 72%, 68%, 46%, 33%, 22%, 15%, 18%, and 38% in comparison to fixed rate case of 6, 9, 12, 18, 24, 36, 48 and 54 Mbps, respectively. In comparison to MH-ARF, it improves PDR as much as 34%.

The rest of the paper is organized as follows: Section II discusses the background information and related work. Section III explains the proposed protocol, PRAM. It is followed by the presentation of ns-2-based experiment results in Section IV. Section V concludes the paper.

II. BACKGROUND AND RELATED WORK

A. Background

IEEE 802.11 and its extensions (IEEE 802.11a/b/g) provide the capability to transmit data at different data rates. For example, IEEE 802.11a/g supports 6, 9, 12, 18, 24, 36, 48 and 54 Mbps. However, it is observed that performance does not improve linearly as the data rate increases even in a single-hop link. This is due to the rate-independent overhead at the PHY (PLCP preamble and header¹) and MAC (SIFS, DIFS and backoff delay) layers [29]. Moreover, this overhead becomes a major part as the data rate increases because the transmission time of the actual payload decreases proportionally.

On the other hand, to increase the aggregate network throughput in a MANET, multiple concurrent communications should be simultaneously successful when they are outside of each other's interference range. It is dictated by two important parameters in wireless communications, called *receive sensitivity* and *capture threshold*. First, for a successful communication, the received signal power must be higher than the receive sensitivity in the presence of path loss over the distance. Second, the received signal power must be strong enough to overcome the influence of noise and interference from all other simultaneous transmissions, *i.e.*, SINR must be higher than the capture threshold [23], [25].

¹PLCP preamble and header at the PHY layer are transmitted at the lowest rate (6Mbps), while the payload is transmitted at a higher rate, which is specified in the control frame

Table I: Characteristics of an 802.11a multirate radio. (Transmit power: 6 dBm, radio propagation model: *two-ray ground reflection* with path loss exponent of 4.)

Data rate (Mbps)	Receive sensitivity (dBm)	Communication range (meters)	Capture threshold (dB)	Interference range (meters)
6	-82	238	6.02	575
9	-81	224	7.78	576
12	-79	200	9.03	536
18	-77	178	10.79	509
24	-74	150	17.04	550
36	-70	119	18.80	470
48	-66	95	24.05	484
54	-65	89	24.56	455

Table I² shows the two parameters at different data rates for a typical 802.11a radio device [24]. A high data rate communication requires a higher receive sensitivity or a shorter communication distance. Also, it requires a higher capture threshold, which means more vulnerability to interference. In other words, although a high rate communication is rendered short-distanced, it still requires the interference range as large as low-rate communications. The parameters in Table I are used in our simulation study detailed in Section IV.

B. Related Work

The research on multirate adaptation targets either single-hop wireless LANs [1], [10]–[12], [18] or multihop networks.

Auto-Rate Fallback (ARF) [12] is the first multirate algorithm, which is sender-based, and was designed to optimize the application throughput in WaveLan II devices. The basic idea of ARF is to use a higher rate upon consecutive successful transmissions and to fall back to a lower rate after a number of consecutive transmission failures. Note that a transmission is judged as a success or a failure based on the ACK signal from the receiver.

Receiver-Based Auto Rate (RBAR) [10] is a receiver-based multirate algorithm. It assumes to use the RTS/CTS handshaking. Upon receiving an RTS frame, the receiver estimates the channel quality based on the *Signal to Interference and Noise Ratio* (SINR) of the received RTS frame and then determines the best data rate that the transmitter must use. The estimated optimal rate is then sent back to the sender by piggybacking in the CTS packet.

A great deal of work on multirate adaptation has been reported in the context of multihop networks [7]–[10], [13], [14], [18]–[21], [24] due to its potential to greatly improve the network throughput. They can be categorized as *proactive* or *on-demand* depending on the routing algorithm used. With a proactive multirate algorithm, each node maintains link costs to each of its neighbors while taking the multirate capability into account. Transition from a single-rate to the corresponding multirate algorithm is conceptually straightforward but at

²Communication range in the Table is computed as the distance at which the received signal power is equal to the receive sensitivity at that rate. *Interference range* in the table refers to the distance at which the SIR at the receiver is equal to the capture threshold when the sender-receiver separation coincides the communication range.

the cost of very high, periodic control overhead due to the multiplicity of route information at multiple data rates.

Sheu *et al.* proposed *Multi-Rate and Multi-Range Routing Protocol* (MR²RP), in which each node runs a *distributed Bellman-Ford* routing algorithm to find the optimal (smallest delay) routing path based on a connectivity matrix [27]. In the matrix, each element corresponds to the delay between two nodes calculated based on the highest data rate supported plus the MAC-layer delay. Awerbuch *et al.* suggested a similar approach based on a proactive routing protocol, DSDV, and a new metric called *Medium Time Metric* (MTM) [7]. It is designed to minimize the total medium time consumed sending packets from a source to destination. Zhai and Fang proposed another new metric, called the *bandwidth distance product* (BDiP), which uses both channel rate and hop distance to determine the best candidate of the next hop [24].

However, the above-mentioned protocols are based on proactive routing algorithms and are known to incur a high control overhead in a mobile environment. Meanwhile, *scsr* [8] and *MR-LQSR* [6] use both proactive (link state) and on-demand (DSR [30]) algorithms but they target static *wireless mesh networks*.

III. PATH-CENTRIC ON-DEMAND RATE ADAPTATION FOR MANETS (PRAM)

This section presents a multirate adaptation algorithm, called *Path-centric on-demand Rate Adaptation for MANETS* (PRAM). In PRAM, a source node floods a RREQ to find a routing path as in a typical on-demand routing protocol such as DSR and AODV. Unique to PRAM is to dictate a data rate for the RREQ and to enforce every intermediate node to use the same rate when forwarding the RREQ. It may discover suboptimal routing paths at the benefit of simplicity and lower control overhead. Key design issues in PRAM are how to determine the data rate for the RREQ and when and how to increase or decrease the data rate.

A. Multirate adaptation in PRAM

On-demand routing algorithms such as AODV use RREQs to find routing paths. Therefore, it is important to use an appropriate data rate when broadcasting a RREQ. For example, if RREQs are forwarded at the lowest rate (6 Mbps), the discovered routing path will consist of long-range links, the communication over which may not be successful at higher data rates. In other words, the data rate for RREQs in essence limits the maximum feasible data rate for the links of the discovered routing paths. An alternative approach is to allow each intermediate node to use a different rate when it forwards a RREQ. For that matter, each node needs to maintain the best data rate for each of its links considering the communication environment in its local neighborhood. However, it is not straightforward for the node to determine the best rate for a broadcast packet such as RREQ.

Optimal data rate for a node pair: PRAM is a path-centric adaptation scheme. A source node determines the data rate for a path to the destination and broadcasts a RREQ at

that rate. Intermediate nodes are obliged to use the same data rate when forwarding the RREQ. When a data rate is too high, there could be a problem of connectivity. On the other hand, when a data rate is too low, the network is unable to realize its maximum capacity allowed by the radio hardware. Therefore, essential to the PRAM protocol is for a source node to determine the destination-specific data rate. Our approach in PRAM is (i) to determine the initial data rate based on the estimation of source-destination distance and (ii) to adapt it based on the path lifetime.

First (initialization), when a source node does not have any information about the destination node, it will try the medium data rate (24Mbps). However, when the source has communicated with the destination in the recent past, it can use the same data rate as an initial try. Second (adaptation), during the communicating with the destination, the source will adapt the rate as follows; (i) If a routing path survives longer than a certain threshold at the current data rate (r_i), the source node may be better off by increasing the rate because the path is considered stable enough to support a higher data rate. The source node will send a *probe RREQ* (pRREQ) message at a higher data rate (r_{i+1}). Note that pRREQ has the same packet format and is handled the same way as RREQ. Probe packet is not a new idea and has been used in single-hop WLANs [8], [12]. When a RREP arrives at the source, it will decide whether it is beneficial to switch to the newly discovered routing path (at r_{i+1}) or not based on the metric, which we will discuss shortly. (ii) If a routing path breaks earlier than the threshold time, the source node will try to find an alternative routing path at the current data rate (r_i). (iii) If the destination is found unreachable due to the limited communication range at the current data rate, the source will broadcast a RREQ again at a decreased rate (r_{i-1}).

Data rate selection metric: In conventional MANET routing algorithms, hop count is used as a metric to compare the candidate routing paths. However, in a real-world deployment of multihop networks, it has been observed that a shortest path is not necessarily the optimal path [4], [6], [8], [28]. In a multirate, mobile environment, it becomes even more complicated. The most agreeable metric would be the channel resource spent to deliver a packet end-to-end. In other words, the maximum aggregate throughput can be obtained by utilizing as little channel resource ($m^2 \cdot sec/bit$) as possible so that the remaining resource can be utilized for other communications.

The metric used in PRAM is the *product of channel space and time* (PST), and is aggregated by using RREP messages with the help from the MAC layer. When a RREP message is delivered from a destination to a source at a data rate r_{i+1} , each intermediate node calculates the PST and piggybacks the accumulated PST in the RREP message. Upon receiving a RREP, the source node obtains the aggregated PST, which can then be used to compare with that at the current rate r_i . The channel time can be roughly estimated by a simple calculation based on the data rate and packet size. One additional consideration is to take the number of retransmissions

at the MAC layer into account as in [4], [19]. For that matter, PRAM requires interactions between the MAC and routing layer, leading to a cross-layer design. The channel space consumed per transmission is approximated as $(\pi \cdot IR^2)$, where IR denotes the interference range, shown in Table I. PRAM decides the optimal data rate that minimizes the aggregated PST.

Link rate optimization: It is oftentimes beneficial to use a higher rate than the source-dictated rate for a particular link. It can help in a temporarily congested area where the fast processing of a packet could allow other nodes to utilize the shared channel. Each node will maintain an optimal data rate for a particular link as in ARF [12]. More specifically, when a node transmits 10 packets successfully for a particular neighbor at the specified data rate (r_i), it increases the data rate for the neighbor to r_{i+1} . When the rate is increased, the first transmission must succeed. Otherwise, the rate immediately falls back to r_i . However, it does not go below the source-dictated data rate. Note that this optimization is implemented at the MAC layer and each node maintains a data rate for each of its neighbors to apply the ARF rule independently.

B. Implementation of PRAM

Fig. 1 shows the overview of the PRAM protocol based on the AODV algorithm [17]. Key changes to the original AODV include (i) routing table entries augmented by data rates, (ii) new control packet, pRREQ, which is sent to discover a new route at a higher data rate, and (iii) RREP packet piggybacked with PST to help determine the best data rate for a routing path. All the data and control packets are transmitted at the source-dictated data rate, but the source dynamically adapts it based on the path lifetime.

Another important consideration in the PRAM protocol is the decision of the unreachability of the destination. In the original AODV [17], if network-wide broadcasting of RREQ fails four times consecutively, the destination is considered unreachable and the source drops all the packets. In PRAM, when the source fails to receive a RREP for a network-wide flood of RREQ, it will decrease the data rate of the next broadcasting of a RREQ until it reaches the lowest data rate available (*i.e.*, 6Mbps). This is because the destination might not be reachable at a higher rate.

Changes in the 802.11 MAC protocol for implementing the PRAM protocol are: (i) When a MAC layer passes a received packet to the network layer, it informs the data rate at which it received. (ii) When the network (routing) layer passes a packet to the MAC for transmission, it specifies the transmission rate for the packet. (iii) For implementing the localized link rate optimization, each node maintains the status of the links to its communicating neighbors. As in ARF [12], it increases and decreases the data rate depending on the recent history of communication successes and failures over the specific link.

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/* When a data packet is ready */
If route is found in routing table [at data rate  $r_i$ ];
  use it to send the packet [at data rate  $r_i$ ];
  [If the path lifetime is longer than a threshold and  $r_i < r_{max}$ ,
   call route_discovery(pRREQ) procedure with  $r_{i+1}$ ];
else, [determine the initial data rate ( $r_i$ );]
  call route_discovery(RREQ) procedure [with  $r_i$ ];

/* When a RREQ is received [at data rate  $r_i$ ] */
Update routing table (backward link) [with data rate];
If self=destination, prepare and send RREP [at  $r_i$ ];
else forward RREQ [at  $r_i$ ];

/* When a RREP is received [at data rate  $r_i$ ] */
Update routing table (forward link) [with data rate];
If self=source,
  [If it is a reply for pRREQ,
   compare PST metric to choose  $r_i$ ];
  send the packet(s) [at  $r_i$ ];
else, [extract, update and piggyback PST;]
  forward RREP [at  $r_i$ ];

/* When a RERR is received [at data rate  $r_i$ ] */
Update routing table (eliminate routes) [with data rate  $r_i$ ];
Compute the set of unreachable due to the broken link;
If the set is empty, stop;
else, Drop the packet(s) destined to one of unreachable;
  forward RERR [at  $r_i$ ];

/* route_discovery procedure [at data rate  $r_i$ ] */
TTL = initial TTL;
While TTL < network_diameter;
  Send RREQ [or pRREQ at data rate  $r_i$ ] with TTL;
  If no RREP within timeout, increment TTL;
  else, stop (RREP received)
While retry_count < retry_limit;
  Send RREQ [or pRREQ at data rate  $r_i$ ] with TTL;
  If no RREP within timeout,
    [decrease data rate;]
    increment retry_count;
  else, stop (RREP received)
Drop the packet(s);

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Figure 1: Overview of the PRAM protocol based on AODV. (All the changes to the original AODV are denoted within brackets.)

IV. PERFORMANCE EVALUATION

A. Simulation environment

The performance of PRAM is evaluated using ns-2 [15], which simulates node mobility, a realistic physical layer, radio network interfaces, and the 802.11 MAC protocol. Our evaluation is based on the simulation of 20~140 mobile nodes located in an area of $1500 \times 300 m^2$. The data traffic simulated is *constant bit rate* (CBR) traffic. 20 CBR sessions are simulated at the packet rate of 20 packets/second. *Random waypoint mobility model* [30] is used in our experiments with the minimum and maximum node speed of 1 m/s and 5 m/s, and a pause time of 0 second. With this mobility model, a node travels (between 1 and 5 m/s) towards a randomly selected destination in the network. After the node arrives at the destination, it travels towards another randomly selected destination. Simulation time is 300 seconds for each run.

The aforementioned simulation parameters are typical in many previous studies on MANET including [26] except that the traffic intensity and the number of nodes (N) are higher than normal. The traffic intensity of 20 sessions with 20 packets/second each could be overwhelming at 6Mbps, but it can be reasonably handled at 54Mbps. N is as many as 140 in our simulation study because a high node density is needed for communications at high data rates. In fact, we

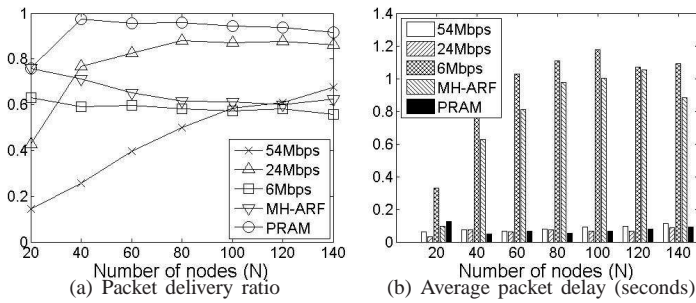


Figure 2: Performance comparison. (PRAM achieves the best performance in the wide range of N in (a). MH-ARF improves over the 6Mbps case but is not comparable to PRAM. In (b), low rate cases exhibit high packet delay due to their slow communication speed. The low packet delay in high rate cases is partly due to their low PDR. PRAM provides low packet delay without deteriorating the PDR.)

are particularly interested in the performance variation with varying the number of nodes in the network.

We compare ten different schemes: fixed data rates of 6 ~ 54Mbps, multihop version of ARF (MH-ARF), and PRAM. In MH-ARF, each node maintains the best rate for each of its neighbors by applying the ARF rule separately. The ARF rule is explained in Section II-B. On the other hand, the fixed-rate cases denote the scenario, where all control and data packets are transmitted at the specified data rate. In a sparse network (e.g., 20 nodes in the network), we expect the 54 Mbps case would suffer the most because of the connectivity problem. But, it will become advantageous as N increases. We have not simulated multirate, proactive routing algorithms in this paper because (i) their performance is not comparable due to high control overhead in a mobile environment, and (ii) in order for the direct comparison of proactive and on-demand (multirate) algorithms, protocol parameters should carefully be chosen.

Performance metrics are *packet delivery ratio* (PDR) and average packet delay. Since PRAM is implemented mostly at the routing layer, we also measured the total control overhead at the routing layer (RREQ/pRREQs, RREPs and RERRs). For PRAM, statistics on the mixture of data rates used are also presented to understand the adaptive behavior of the PRAM protocol.

B. Simulation results

Fig. 2 compares PDR and average packet delay of the fixed rate cases, MH-ARF and PRAM. For clarity, we show only three (54Mbps, 24Mbps and 6Mbps) out of the eight fixed rate cases. Fig. 2(a) shows the PDR versus N . The 54Mbps case does not function well as shown in the figure, particularly with a small N . This is mainly due to the lack of end-to-end connectivity. However, its performance increases rapidly as N increases. A similar pattern is observed for other high data rates. In the 6Mbps case, the PDR is the highest when N is 20 and decreases as N increases. What matters at 6Mbps is not the end-to-end connectivity, but the traffic intensity because control traffic (broadcast of RREQs) increases with N . MH-ARF performs better than the 6Mbps

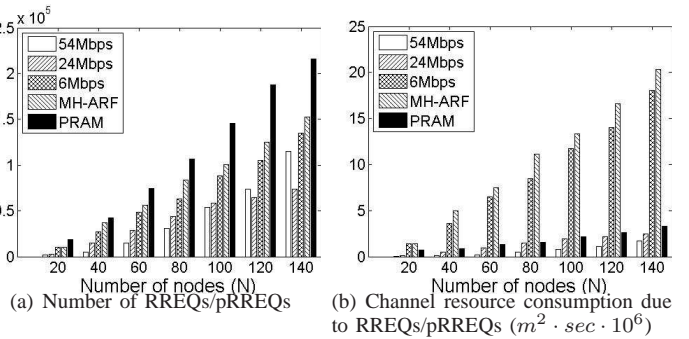


Figure 3: Control overhead. (The number of RREQs is the highest in PRAM in (a). However, the channel resource consumption, measured in $m^2 \cdot sec$, is relatively small as shown in (b). Note that RREQs/pRREQs are responsible for the major part of routing layer control overhead. RREPs and RERRs take less than 10% of the total control overhead.)

case but the corresponding improvement is not significant. Note that PRAM achieves the best performance in the entire range of N as shown in Fig. 2(a). The main reason behind the superior performance of PRAM is that it uses a combination of all available data rates to maximize the network performance.

Fig. 2(b) shows the average packet delay versus N . The 6Mbps case has the highest packet delay because of its slow packet transmission speed. PRAM performs on par with the high rate cases as shown in the figure. However, the low packet delay for high rate cases does not represent their true performance because their PDR is low, and the computation of the average packet delay does not take the lost packets into account. On the other hand, PRAM's low packet delay in Fig. 2(b) demonstrate its exceptional performance because its PDR is the highest as shown in Fig. 2(a). The packet delay of MH-ARF is lower than the 6Mbps case but, again, it is still much higher than the proposed PRAM protocol.

A caveat of PRAM is its additional control overhead at the routing layer because it broadcast RREQs to use a higher-rate path whenever the preset condition is satisfied. More RREQs (pRREQs) incur more RREPs. The number of RERRs could be higher too because the new path at a higher rate could break more easily. Since RREQs are the dominant routing layer control overheads in AODV as discussed in [26] as well as observed in our simulation study, we compare the number of RREQs only. In Fig. 3(a), it is observed that the number of RREQs increases as N increases. This is expected because RREQs are broadcast messages and every node will forward it once as long as its TTL is large enough (network-wide broadcast). Another clear trend is that PRAM produces the largest number of RREQs as discussed above. It is noted, however, that the number of RREQs does not offer the correct level of overhead because a RREQ at 6Mbps consumes more channel resource, or PST mentioned in Section III-A, than that at 54Mbps. Fig. 3(b) compares the PST consumed by RREQs during the simulation runs. Although the number of RREQs in PRAM is the largest in Fig. 3(a), the corresponding PST is relatively small compared to others. In fact, the 6Mbps case consumes the second largest PST because each RREQ takes

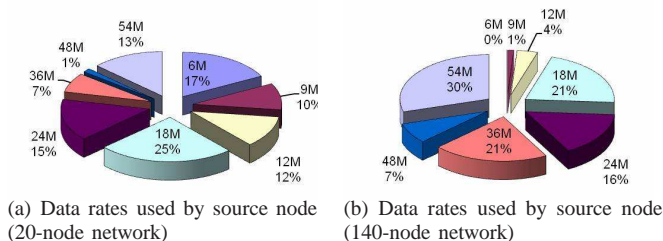


Figure 4: Statistics of data rate in PRAM. (In the 20-node network, low rate communications dominate the network as shown in (a). More nodes in 140-node network have a chance to use high data rates as in (b).)

a longer channel time.

In order to understand how PRAM improves the network performance, we collect statistics about data rate of the discovered routing paths. Figs. 4(a) and 4(b) show the mixture of data rates used in 20- and 140-node networks, respectively. In the 20-node network, the mixture is 17%, 10%, 12%, 25%, 15%, 7%, 1% and 13% for 6~54 Mbps. About 80% of routing paths use 6~24 Mbps. On the other hand, in the 140-node network, the mixture becomes 0%, 1%, 4%, 21%, 16%, 21%, 7%, and 30%, and more than 95% of routing paths use 18~54 Mbps. In other words, the PRAM protocol discovers routing paths at lower rates when network is sparse and at higher rates when network is dense.

In summary, PRAM uses a good mixture of data rates for routing paths depending on their source-destination separation and node density and thus, utilizes minimal channel resource to significantly improve the network's packet delivering capability without degrading the packet delay.

V. CONCLUSION AND FUTURE WORK

This paper discusses complex tradeoffs in a mobile environment and presents a new multirate adaptation protocol in the context of 802.11 MAC and AODV without incurring a high control overhead. A key idea of the proposed PRAM protocol is a *path-centric* or *top-down* approach. In other words, it finds an optimal data rate for a path and dynamically adapts it based on link/path lifetime. Extensive performance study based on ns-2 network simulator shows that PRAM performs better than fixed-rate scenarios (6~54Mbps) as well as the multihop version of ARF (MH-ARF) in terms of PDR and packet delay in the entire range of node density owing to the adaptive behavior of PRAM under different network conditions.

PRAM opens many interesting directions of research to pursue. For example, we are currently investigating the application of PRAM in multi-radio, multi-channel wireless mesh networks. Second, the performance and control overhead of PRAM will be measured with various mobility models and compared against proactive algorithm-based multirate adaptation protocols [7], [24], [27]. Third, accurate estimation of path lifetime in real mobile environment and its impact on the effectiveness of the PRAM protocol is another interesting research subject.

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